

Easytrak Nexus 2 USBL, Model 2692





Key features

- Bi-directional Sigma 2 spread spectrum acoustics
- Optimised beacon refresh rate
- 16 target tracking
- · Geographical navigation overlays

- EasyCal 2 embedded calibration tool with AutoCal Wizard
- With 1100, MiQ data telemetry, Multi-Fire common interrogate
- Sound velocity profile upload facility

Easytrak Nexus 2 Overview

The Nexus 2 is the second generation of Easytrak digital USBL systems designed as a highly advanced positioning and tracking system that is quick to deploy and straightforward to operate. Featuring age Sigma 2 acoustic protocols, the Nexus 2's digital spread spectrum transmissions provide a secure acoustic link with very low susceptibility to interference, enabling precise and reliable positioning over an extended operational range.

Able to determine the positions of up to 16 dynamic subsea targets simultaneously, Nexus 2 is ideal for many deep or shallow water applications where multiple assets are to be tracked. These operations can include UXO surveys utilising several magnetometers or sidescan sonars, diving operations, and for use at offshore worksites where several vehicles may be in use concurrently. The long range capability and exceptional accuracy specifications make Nexus 2 particularly effective for long layback towed applications.

When coupled with 1100 Series positioning beacons, Nexus 2 provides Multi-Fire and MiQ Data telemetry functionality.

Nexus 2 Technical Specification

NEXUS 2 CONSOLE, MODEL EZT-2692

Provides DC power, high speed digital communications to the transceiver with an embedded graphical navigation interface. Supplied with monitor, keyboard and mouse.

Dimensions	19" Rack mount. 2U, 482 x 88 x 345mm						
Weight	5.4kg						
Power requirements	90 to 250 Vac at 250 VA maximum						
Connection to transceiver	Rear panel connector						
Built-in PC	Industrial i7 running embedded W10, 64GB SSD						
Temperature	Operating: -10° to +40°C						
	Storage: -20° to +50°C						
Front panel indicators	LED indicators for power and serial status.						
Serial communications	4 x RS-232 External Input Port. 3 x Data Out Ports						
Data Output	aae format V1 and V2, TP-II2EC, TP-EC W/PR, Simrad 300P,						
	Simrad 309, Simrad \$PSIMSSB, Pseudo \$GPRMC, NMEA \$GPGGA,						
	NMEA \$GPVTG, NMEA \$GPTLL, Pseudo \$GPGGA, KLEIN 3000 (Quick set)						
	Multiple outputs available						
Compass Input	SGB-HTDS, SGB-HTDt, NMEA HDT,HDM, HDG						
Compass Input VRU Input	SGB-HTDS, SGB-HTDt, NMEA HDT,HDM, HDG TCM-2.X, \$HCXDR , TSSI						
VRU Input	TCM-2.X, \$HCXDR, TSSI						
VRU Input	TCM-2.X, \$HCXDR , TSSI NMEA; GLL, GGA, RMC						
VRU Input GPS / DGPS Input	TCM-2.X, \$HCXDR , TSS1 NMEA; GLL, GGA, RMC Geo Referenced Graphical Overlay. GeoTiff, DXF						
VRU Input GPS / DGPS Input Target Heading Input	TCM-2.X, \$HCXDR , TSSI NMEA; GLL, GGA, RMC Geo Referenced Graphical Overlay. GeoTiff, DXF NMEA HDM, HDT, HDG, PNI TCM2						
VRU Input GPS / DGPS Input Target Heading Input Target Depth Input	TCM-2.X, \$HCXDR , TSSI NMEA; GLL, GGA, RMC Geo Referenced Graphical Overlay. GeoTiff, DXF NMEA HDM, HDT, HDG, PNI TCM2 NMEA DBT, DBK, DBS, DPT, AAE						
VRU Input GPS / DGPS Input Target Heading Input Target Depth Input Time in	TCM-2.X, \$HCXDR , TSSI NMEA; GLL, GGA, RMC Geo Referenced Graphical Overlay. GeoTiff, DXF NMEA HDM, HDT, HDG, PNI TCM2 NMEA DBT, DBK, DBS, DPT, AAE GPS Time synch						
VRU Input GPS / DGPS Input Target Heading Input Target Depth Input Time in Responder Output	TCM-2.X, \$HCXDR , TSSI NMEA; GLL, GGA, RMC Geo Referenced Graphical Overlay. GeoTiff, DXF NMEA HDM, HDT, HDG, PNI TCM2 NMEA DBT, DBK, DBS, DPT, AAE GPS Time synch Positive 12V pulse 5ms long						
VRU Input GPS / DGPS Input Target Heading Input Target Depth Input Time in Responder Output USB	TCM-2.X, \$HCXDR , TSSI NMEA; GLL, GGA, RMC Geo Referenced Graphical Overlay. GeoTiff, DXF NMEA HDM, HDT, HDG, PNI TCM2 NMEA DBT, DBK, DBS, DPT, AAE GPS Time synch Positive 12V pulse 5ms long 6 ports available, 2 on front panel						



Nexus 2 Technical Specification

TRANSCEIVER, TYPE EZT-2782 and EZT-2780 SPECIFICATIONS

Factory calibrated multi-element transceiver head complete with integral AHRS, depth sensor and temperature sensor.

Material	Stainless steel						
Weight in air/water	2782: 16kg/11kg 2780: 21kg/15kg						
Dimensions	2782: 200mm Ø x 432mm 2780: 200mm Ø x 432mm						
Temperature	Operating: -10° to +40°C Storage: -20° to +50°C						
Depth rating	30m						
Electrical supply	48Vdc (from console)						
Depth sensor (Pressure Sensor)	5 bar, accuracy 0.25% between -10° to +40° C						
Temperature sensor	1° resolution between -10° and +40° C						
Frequency band (MF)	18 - 32 kHz						
Tracking beam pattern	2782: 180° 2780: 170° calibrated acoustic coverage, optimum performance within 150°						
Transmitter	Variable, typical max 192dB re 1µPa at 1m						
Compatible transponders	aae Sigma 1, Sigma 2 Digital Spread Spectrum and aae Tone channels, aae V-NAV channels. HPR 400 channels. 1100, 1000, 1200A, 1300A Series beacons, Digital Depth Transponders, aae Release and Telemetry beacons						
Interrogation rate	>2Hz refresh rate. Internally set or external key						
System	Externally assessed for immunity and emissions; conforms to 89/336/EEC. RoHS compliant						
Cable length	Max 150m						



Transceiver Performance

Accuracy is based on the correct speed of sound being entered, no ray bending and an acceptable S/N ratio

Position repeatability, calibrated and measured with SNR > 20dB rel.1µPa in a controlled test environment

Tranceiver	Console	Beam Pattern	Acoustic precision degrees	Acoustic % slant range	Internal AHRS precision	Acoustic + internal AHRS %	Acoustic + external AHRS %	Max range	Range resolution	UK Export control
EZT-2686-N	EZT-2692	180°	0.25° DRMS	0.45%	0.5°	1.49%	0.45%	995m	0.01m	No
EZT-2686-C	EZT-2692	180°	0.25° DRMS	0.45%	0.5°	1.49%	0.45%	2000m	0.01m	Yes
EZT-2780-N	EZT-2692	170°	0.07° DRMS	0.12%	0.5°	1.17%	0.45%	995m	0.01m	No
EZT-2780-C	EZT-2692	170°	0.07° DRMS	0.12%	0.5°	1.17%	0.45%	3000m	0.01m	Yes

Options

Tilted head, 30° (EZT-2780-T)

